



Sparse Signal Processing

Parcimonie en Traitement du Signal

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Two inverse problems in audio processing

- **Source localization**
 - ✓ S. Nam
- **Audio inpainting**
 - ✓ A. Adler, N. Bertin, V. Emiya,
M. Elad, C. Guichaoua, M. Jafari,
M. Plumley

small-project.eu



echange.inria.fr



Source localization with S. Nam



Localization with few microphones



● Possible goals

- ✓ **localize** emitting sources
 - ✓ **reconstruct** emitted signals
 - ✓ **extrapolate** acoustic field

• **Linear inverse problem**

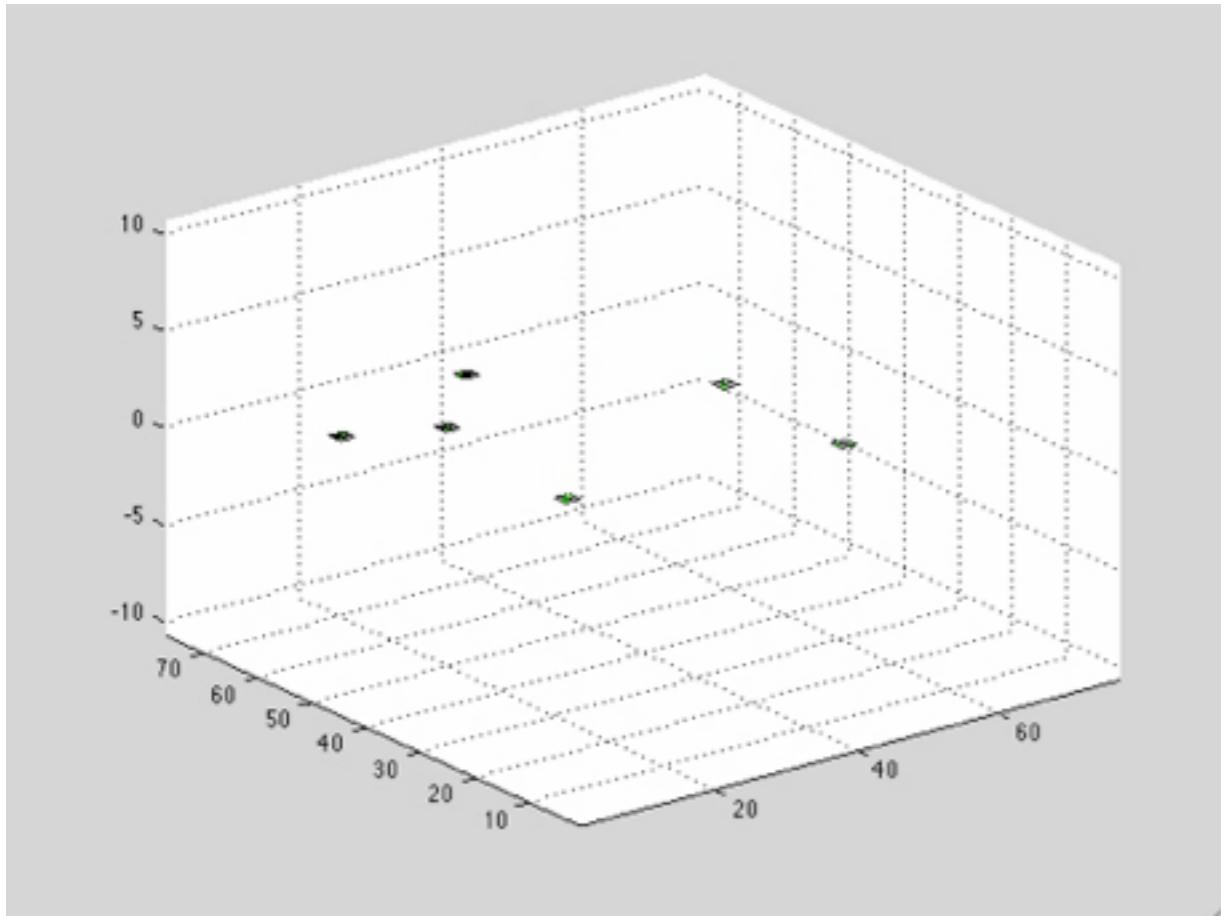
$$\mathbf{y} = \mathbf{M}\mathbf{x}$$

time-series recorded at sensors $\in \mathbb{R}^m$

(discretized) spatio-temporal acoustic field $\in \mathbb{R}^N$

● Need a model

Localization with few microphones



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Physics-driven design of model

- Pressure field

$$p(\vec{r}, t)$$

- Wave equation on a domain

$$(\Delta p - \frac{1}{c^2} \frac{\partial^2}{\partial t^2} p)(\vec{r}, t) = s(\vec{r}, t), \quad \vec{r} \in \dot{\mathcal{D}}$$

- Boundary + initial conditions, e.g.

$$\frac{\partial p}{\partial n}(\vec{r}, t) = 0, \quad \vec{r} \in \partial \mathcal{D}$$

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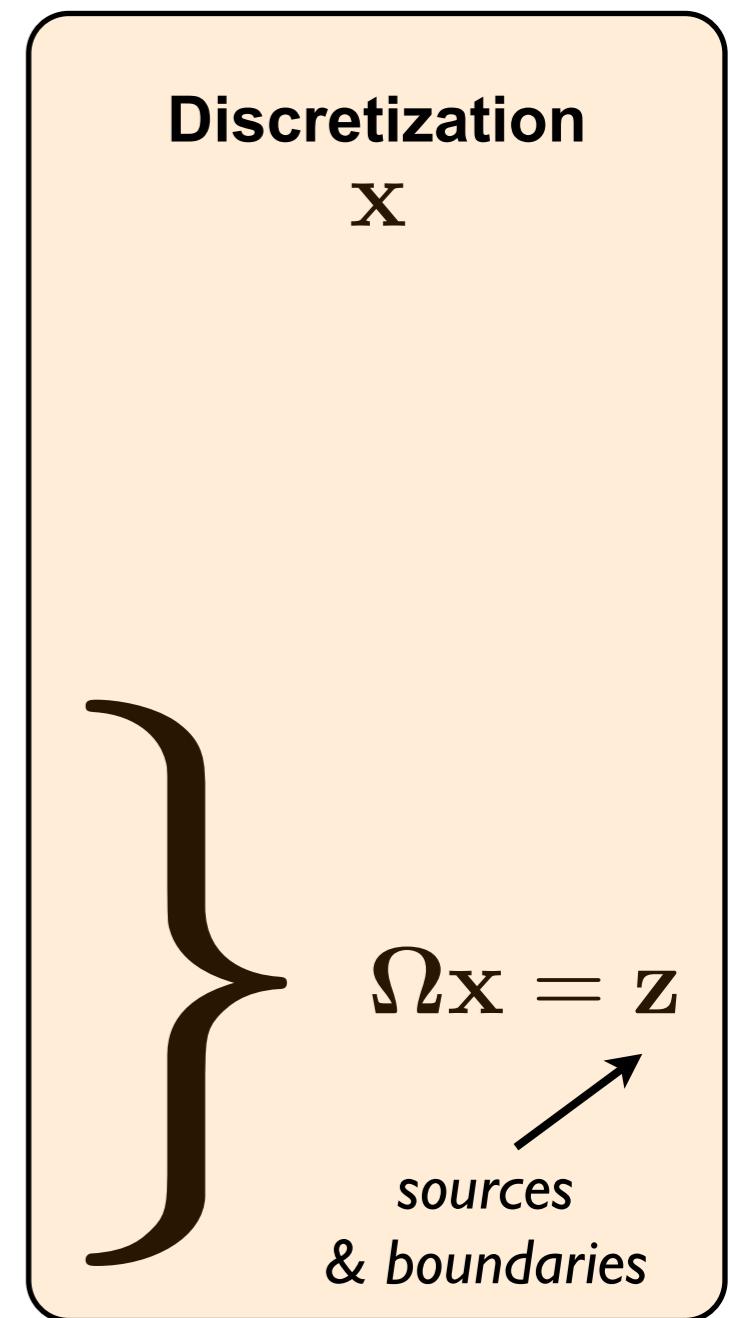
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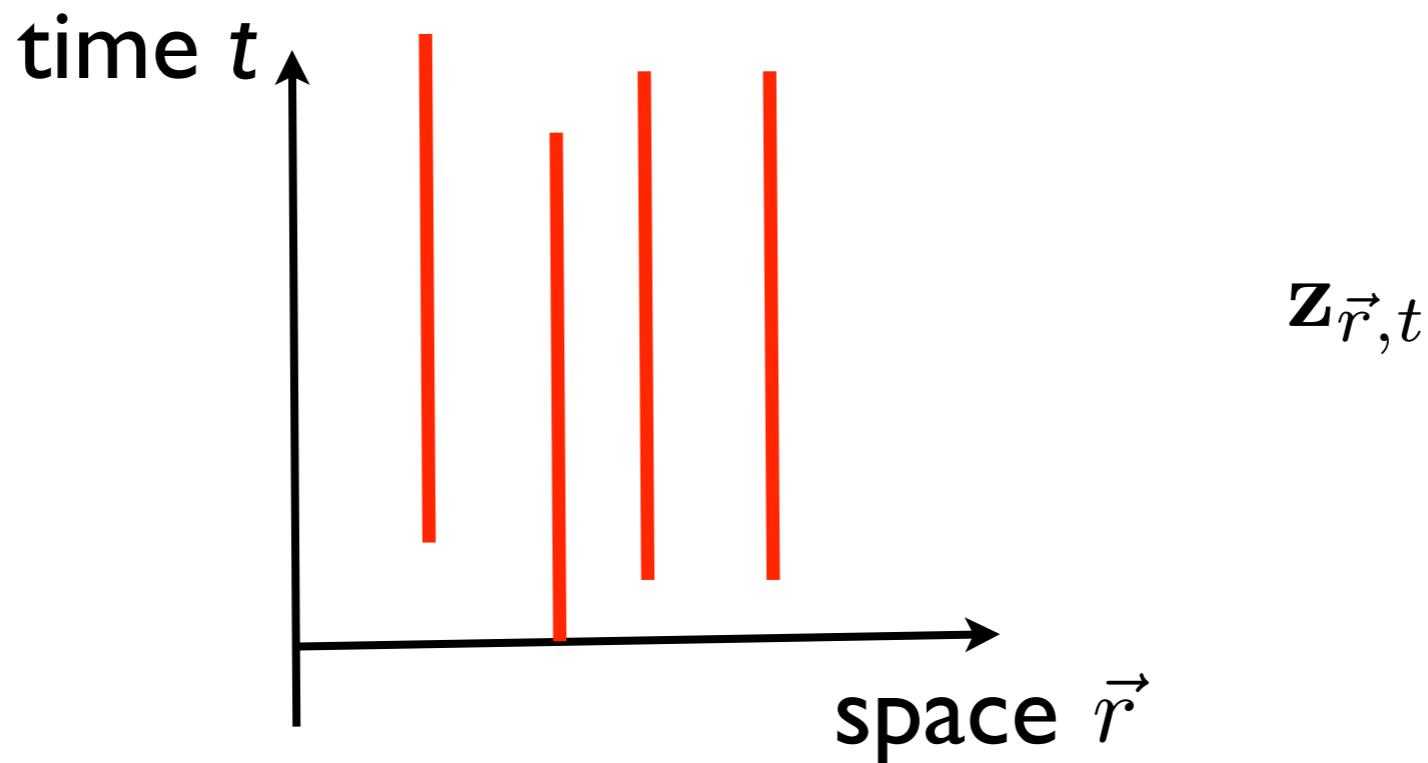
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Group sparse source model

- Few non-moving sources = spatially sparse



Group sparse regularization

- Inverse problem $\mathbf{y} = \mathbf{M}\mathbf{x}$

- Regularization with mixed norm

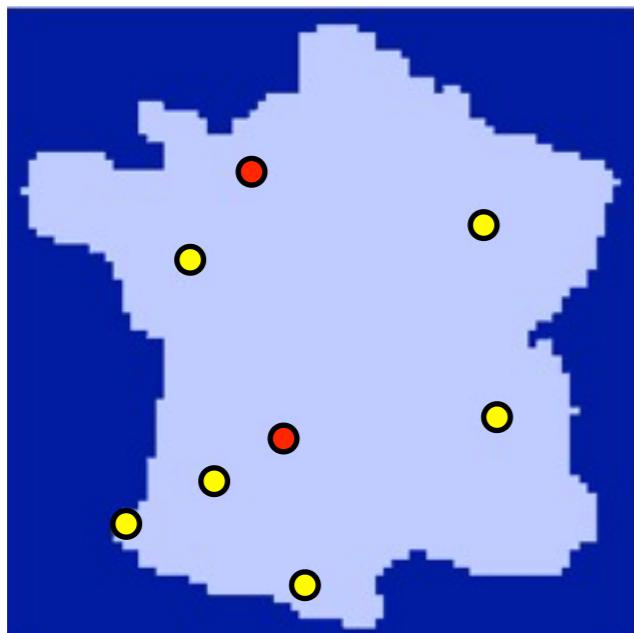
$$\hat{\mathbf{x}} = \arg \min_{\mathbf{x}} \frac{1}{2} \|\mathbf{y} - \mathbf{M}\mathbf{x}\|_2^2 + \lambda \|\Omega\mathbf{x}\|_{1,2}$$

- ◆ Convex optimization: efficient & provably convergent algorithms
- ◆ Promotes group sparsity, cf Kowalski & Torresani 2009, Eldar & Mishali 2009, Baraniuk & al 2010, Jenatton & al 2011

Sparse Field Reconstruction

- **Setting**

- ✓ 2D+t vibrating plate 77x77
- ✓ 2 sources, random location
- ✓ 6 microphones, random location
- ✓ known complex boundaries
- ✓ ground truth generated with naive discretization



- **Results**

Ground truth

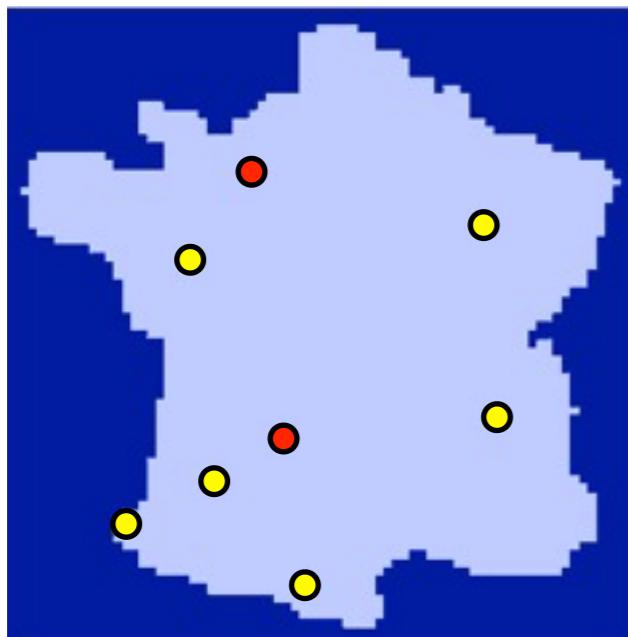
Sparse reconstruction

S. Nam and R. Gribonval. Physics-driven structured cosparse modeling for source localization, ICASSP 2012

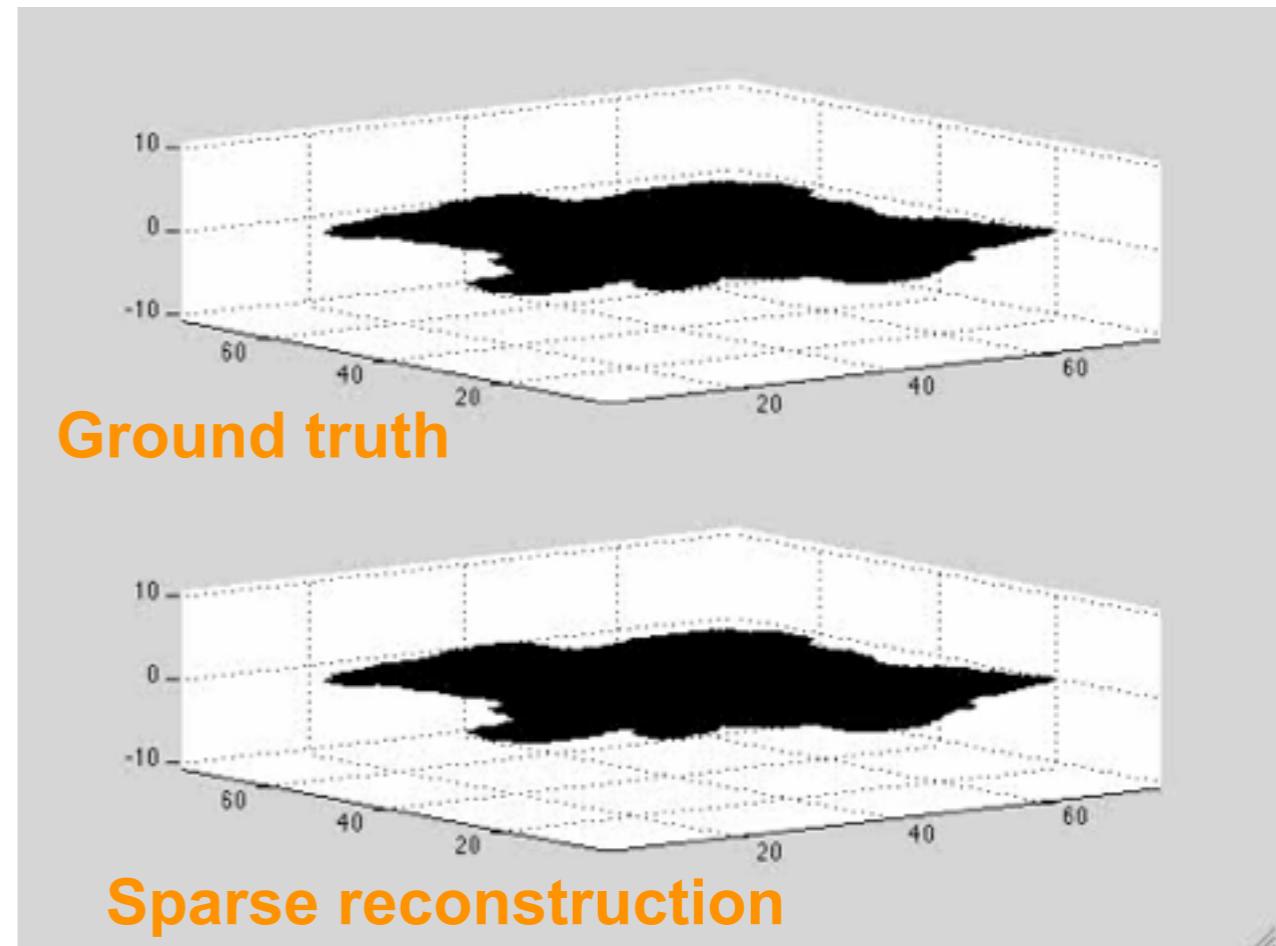
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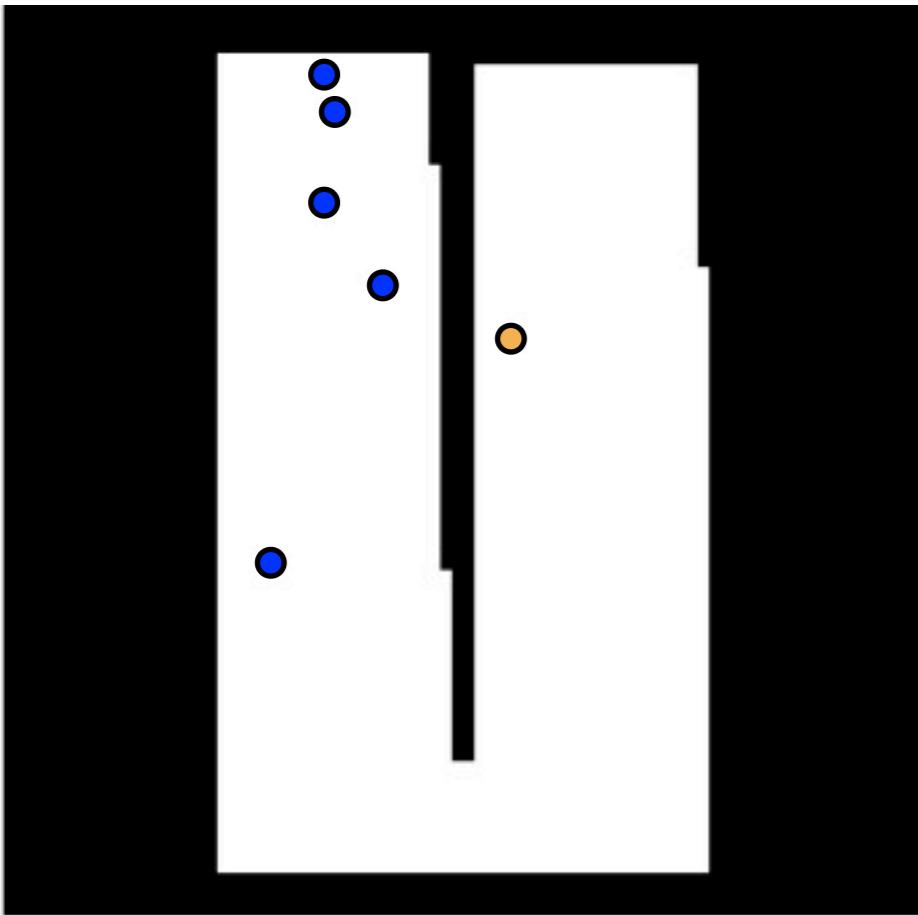
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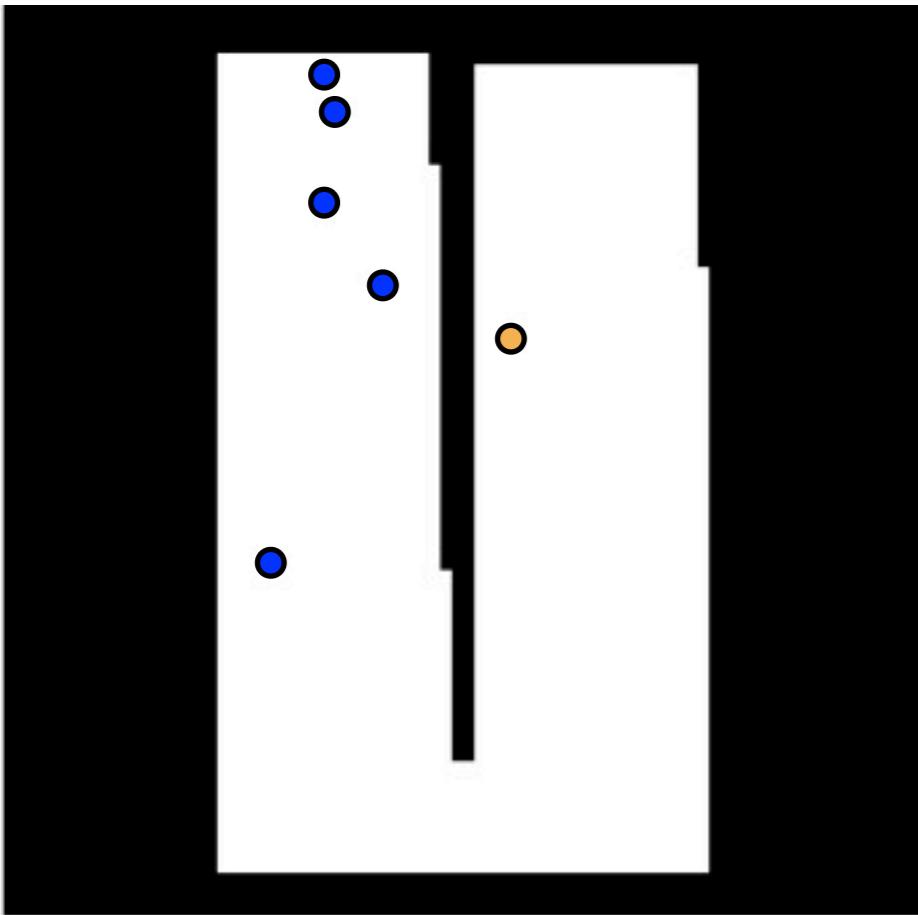
Localizing the source next door

- Domain, Source and Microphones



Localizing the source next door

- Domain, **Source** and **Microphones**

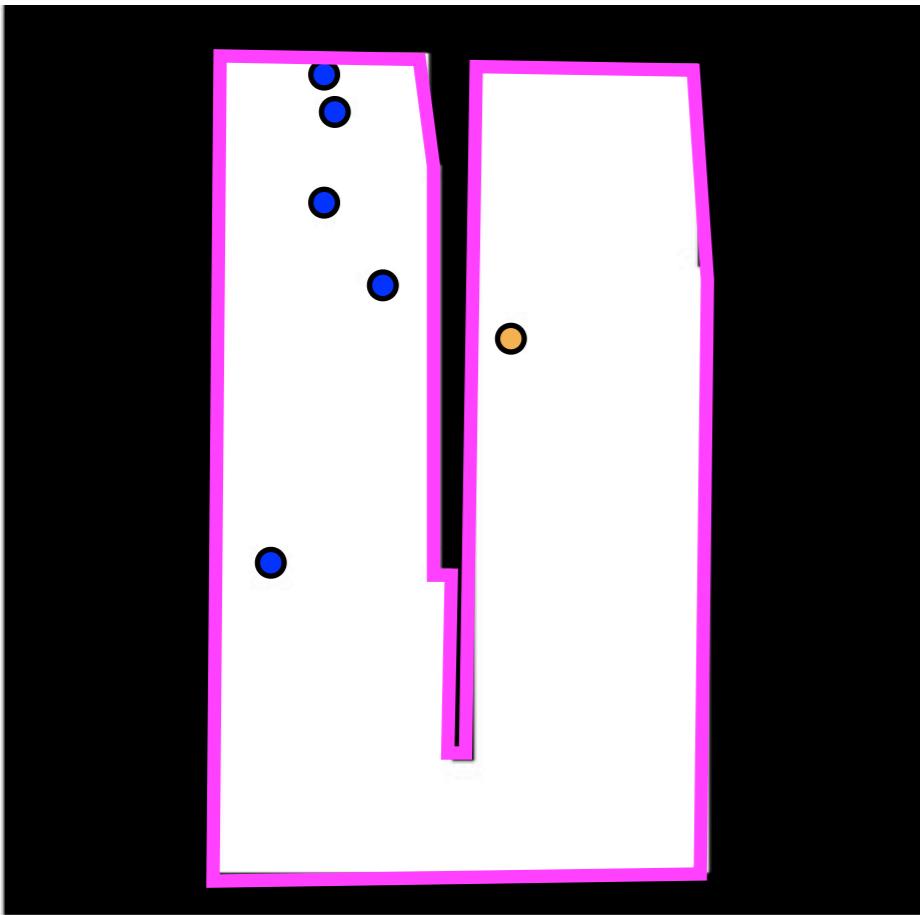


- **Sparse source localization**



Localizing the source next door

- Domain, **Source** and **Microphones**
- **Sparse source localization**



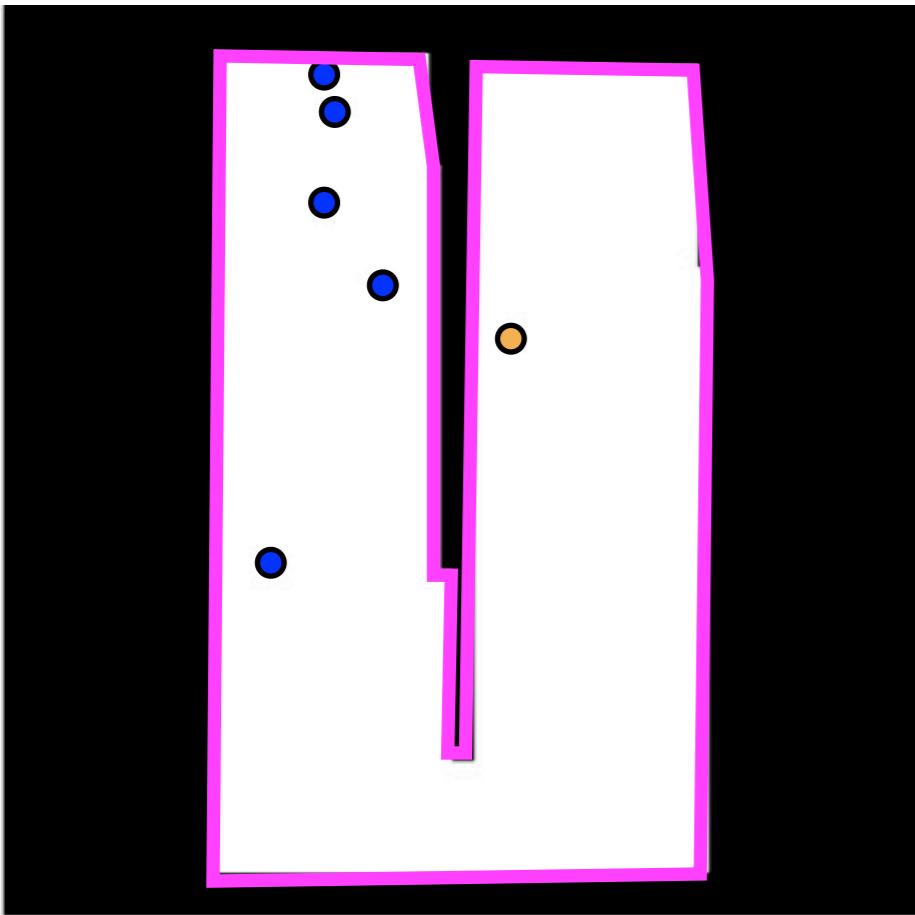
Reasons of success

- sparsity of sources
- *known* room shape
- *known* boundaries



Localizing the source next door

- Domain, **Source** and **Microphones**
- Sparse source localization



Reasons of success

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What if shape
is unknown ?



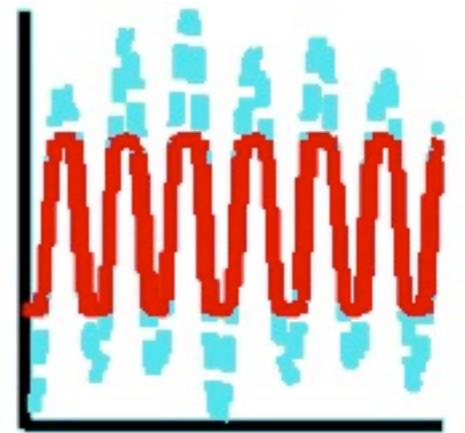
Audio inpainting

with A. Adler, V. Emiya, M. Elad, M. Jafari, M. Plumbley

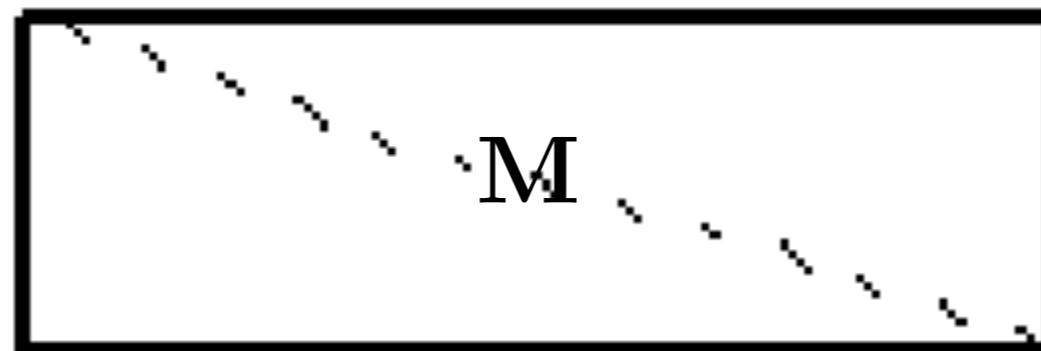


Declipping as a linear inverse problem

- Original (unknown) samples \mathbf{x}
- Clipped (observed) samples \mathbf{y}
- Subset of reliable samples $\mathbf{y}_{\text{reliable}}$
- **Linear inverse problem**

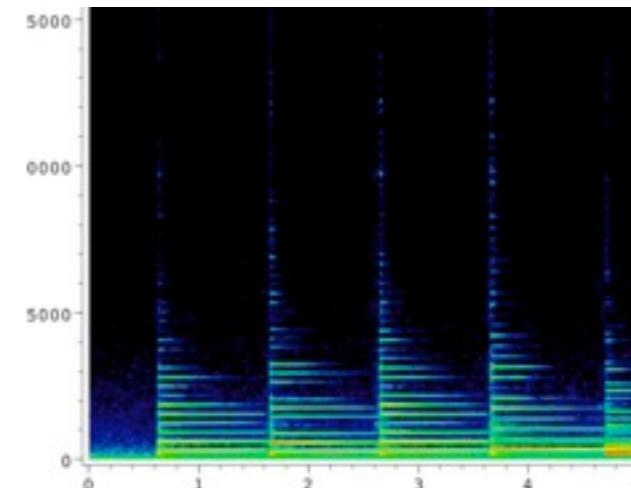
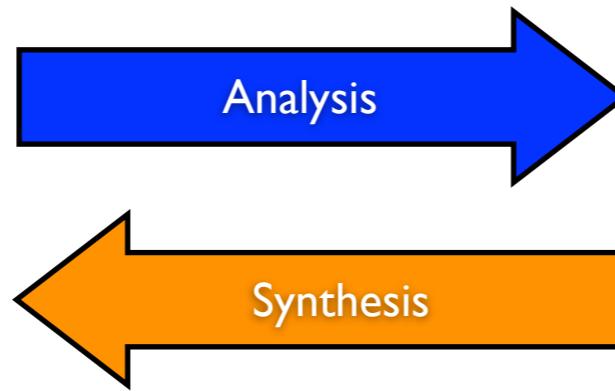
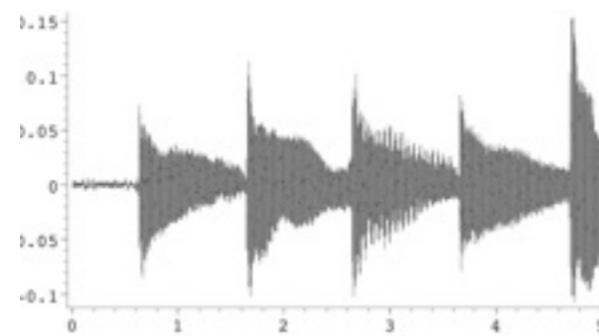


$\mathbf{y}_{\text{reliable}} =$



Sparse audio models

- Time domain
- Time-frequency domain



(Black = zero)

$$\mathbf{x} \approx \mathbf{Dz}$$

Audio Declipping

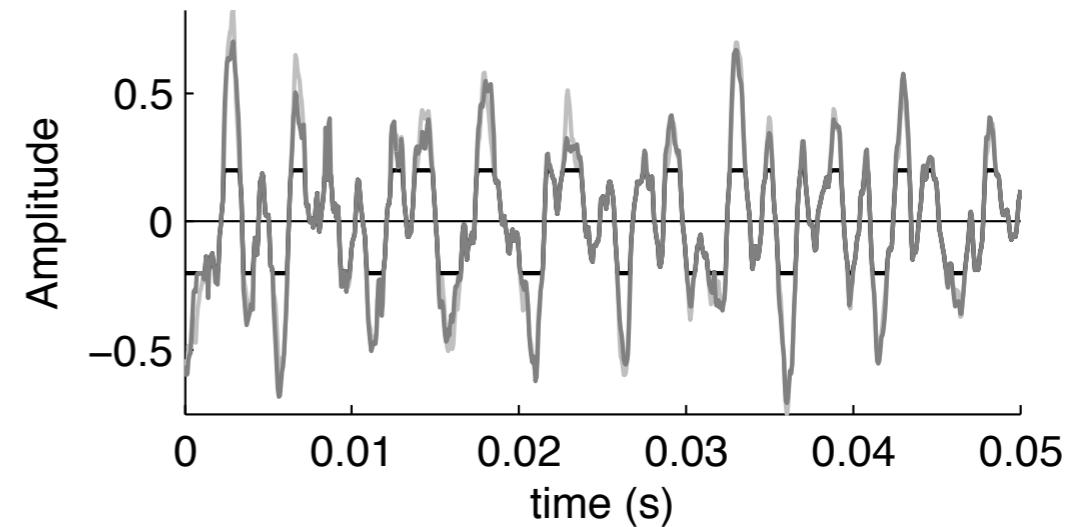
- **Model**

- ✓ sparsity in time-frequency dictionary $\mathbf{x} = \mathbf{Dz}$

- **Algorithm:**

- ✓ find sparse coefficients $\hat{\mathbf{z}}$ such that $\mathbf{y} = \mathbf{MD}\hat{\mathbf{z}}$
 - ◆ (Orthonormal) Matching Pursuit (*Mallat & Zhang 93*)

- ✓ estimate $\hat{\mathbf{x}} = \mathbf{D}\hat{\mathbf{z}}$



A. Adler, V. Emiya, M. Jafari, M. Elad, R. Gribonval and M. D. Plumbley, Audio Inpainting, IEEE Trans Audio Speech and Language Proc., 2012

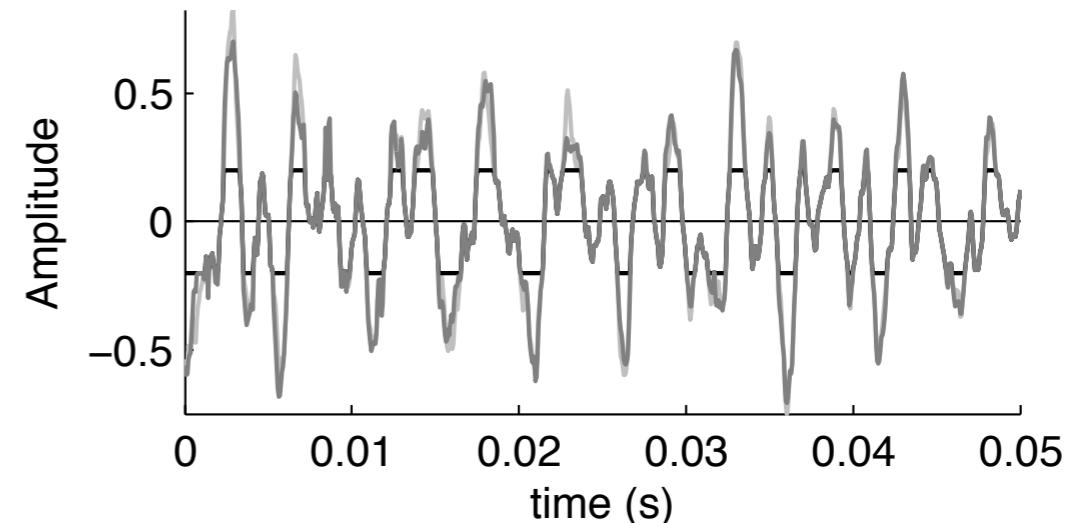
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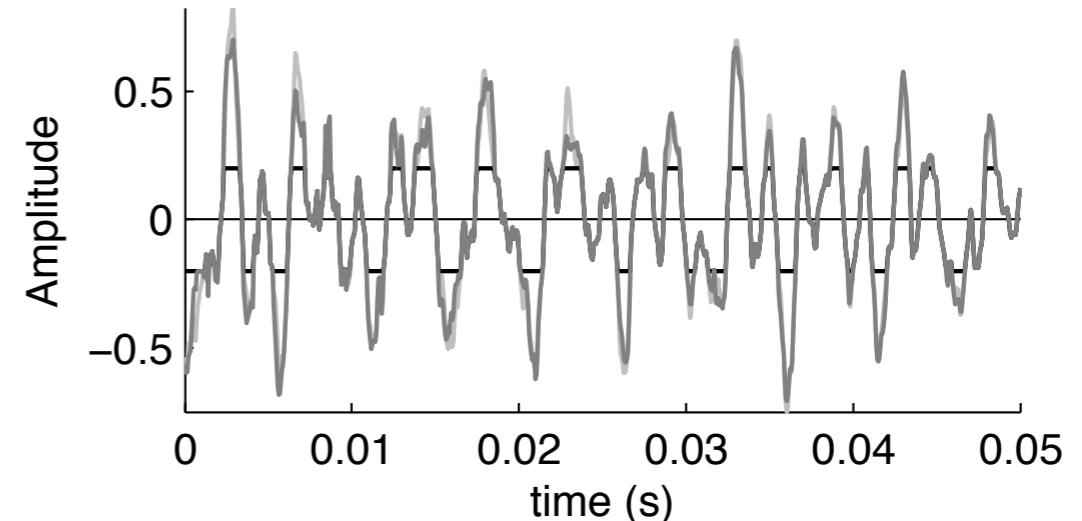
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Clipped



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Audio Declipping

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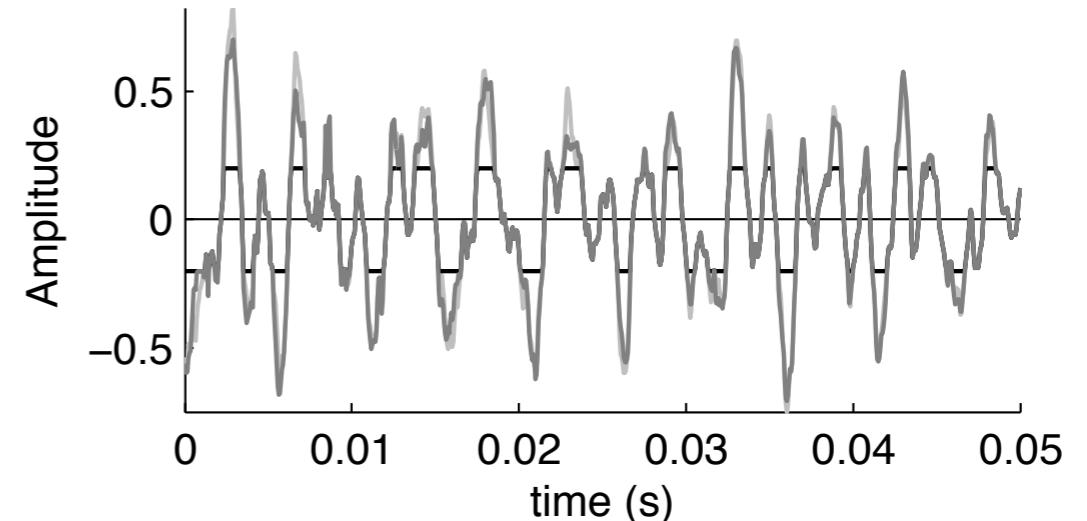
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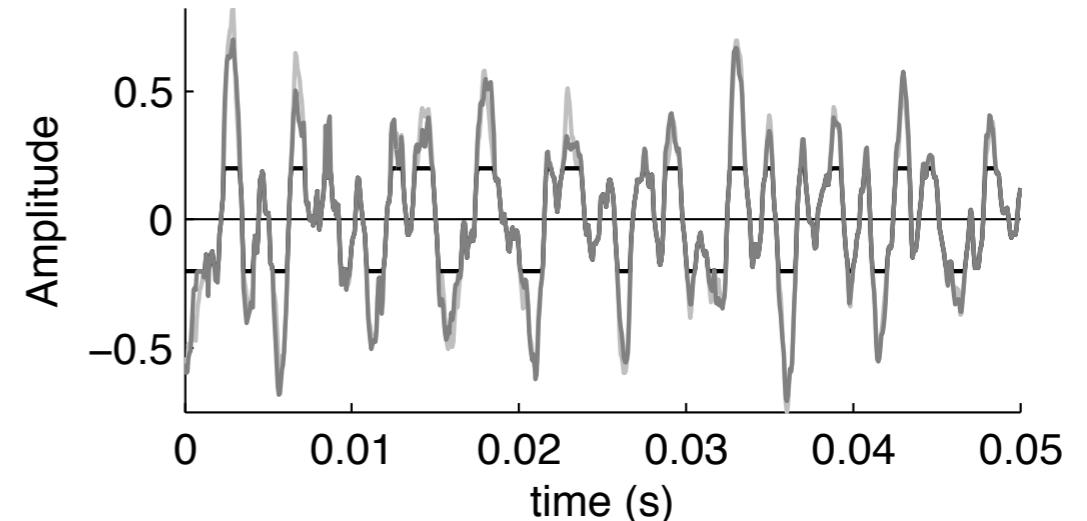
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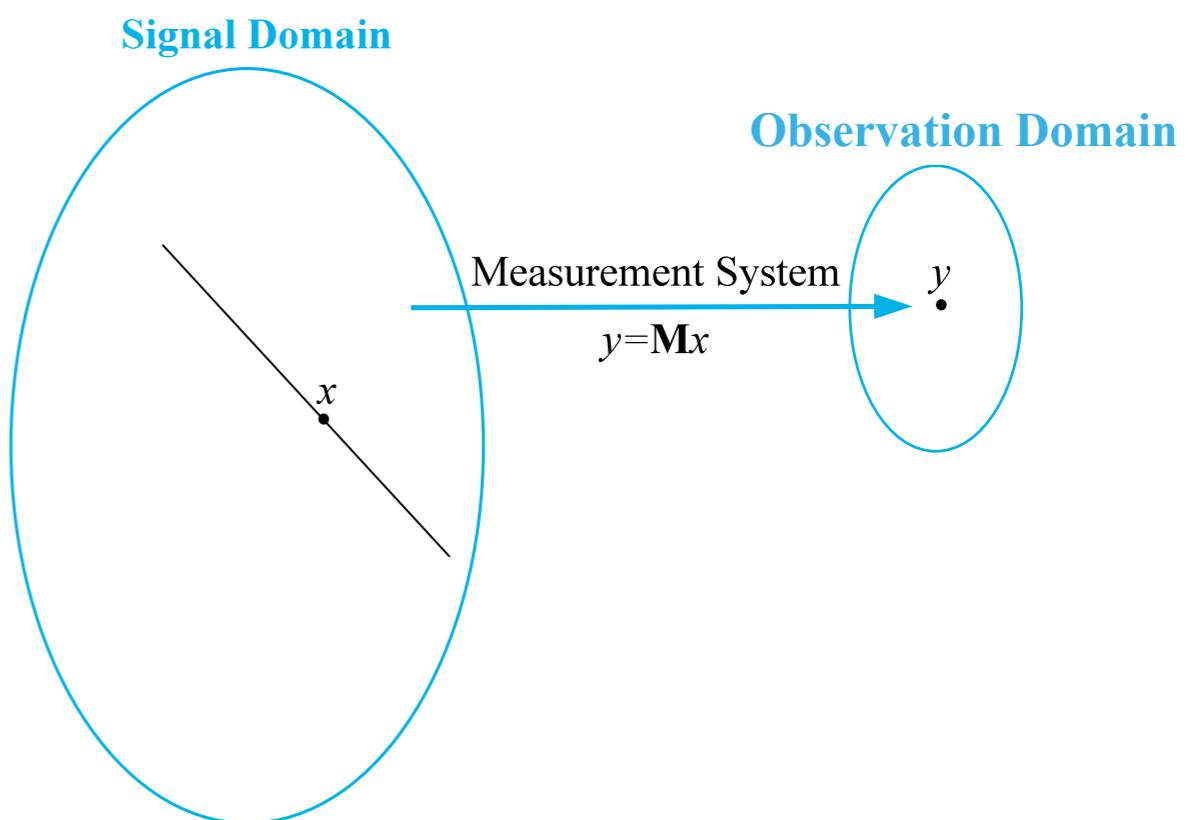
Clipped Declipped Original



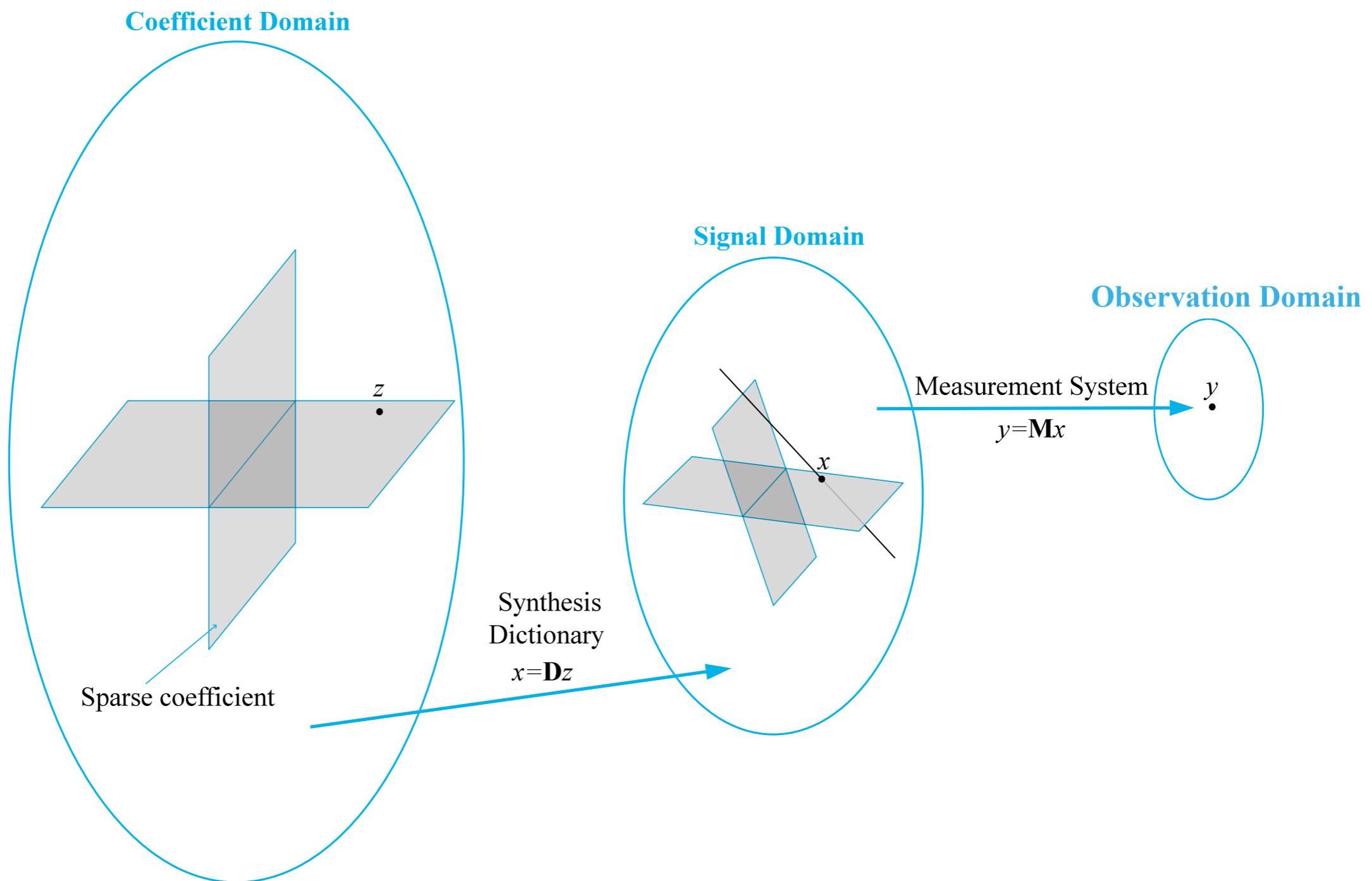
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Summary & next challenges

Inverse problems ...



Inverse problems ... and sparse models



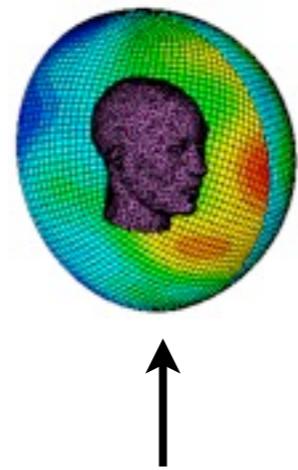
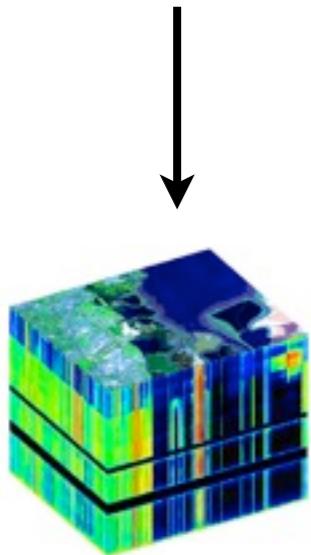
Choosing a model

- **Expert knowledge (Fourier / wavelets)**
 - ✓ Harmonic analysis / physics
 - ✓ *Evolution of species*
- **Training from corpus**
 - ✓ Dictionary learning
 - ✓ *Individual experience*
- **«Online» training / adaptivity ?**
 - ✓ Blind Calibration & Deconvolution
 - ✓ *Adaptation to new environment*

Data Jungle

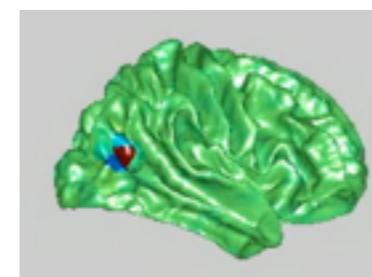
- New data beyond signals and images

✓ Hyperspectral
Satellite imaging

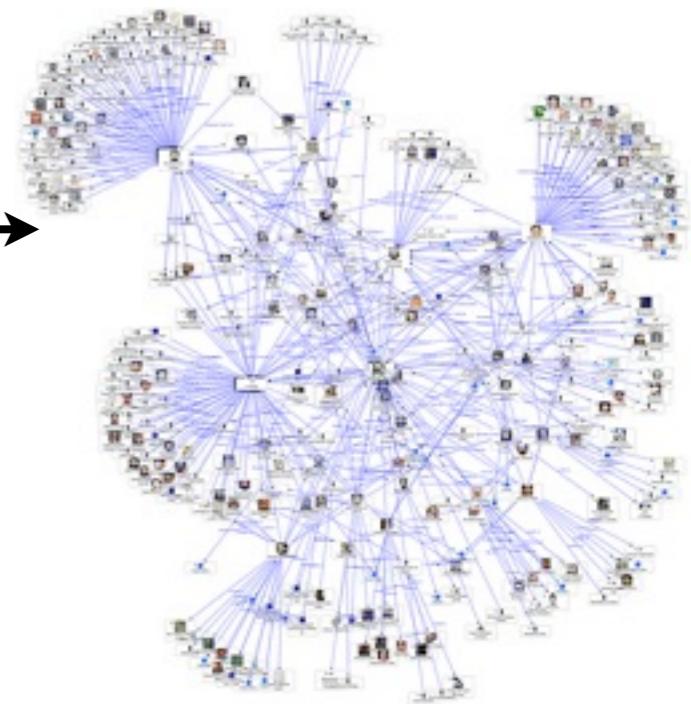


✓ Spherical geometry
Cosmology, HRTF (3D audio)

✓ Graphs
Social networks →
Brain connectivity



✓ Vector valued
Diffusion tensor



Key problem

Versatile low-dimensional models

What's next, please ?

- **Unified efficient data processing**

- ◆ Signal processing
- ◆ *Machine Learning*

- **Ground-breaking advances**

- ◆ Compressive acquisition and compressive learning
- ◆ Sparse models beyond dictionaries

- **Upcoming applications**

- ◆ Inpainting / super-resolution (image/video/audio)
- ◆ Distributed video coding
- ◆ Astronomical imaging (interferometry)
- ◆ Low-dose biomedical imaging (CT & IRM)
- ◆ Audio recording @ high spatial resolution
- ◆ Low-power compressive-sensors
- ◆ Dynamic high-resolution brain imaging
- ◆ ...



projection, learning and sparsity for efficient data processing



PLEASE

projection, learning and sparsity for efficient data processing



SPECIAL THANKS

- **Frédéric Bimbot**
- **Nancy Bertin, Emmanuel Vincent**
- **Current Docs & Postdocs:**
 - ✓ Alexis Benichoux, Anthony Bourrier, Srdjan Kitic, Lei Yu, Cagdas Bilen, ...
- **Stéphanie Lemaile**
- **Jules Espiau**

